

## THE ULAM-HYERS STABILITY OF AN ORDINARY DIFFERENTIAL EQUATION VIA GRONWALL LEMMAS

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**Abstract.** Following [I.A. Rus, Gronwall lemma approach to the Hyers-Ulam-Rassias stability of an integral equation, in: *Nonlinear Analysis and Variational Problems*, Panos Pardalos, Themistocles M. Rassias, Akhtar A. Khan (ed.), pp. 147-152, Springer, 2009], we study the Ulam-Hyers stability of some ordinary differential equations based on Gronwall lemmas.

**Keywords.** Cauchy problem; Differential equation; Integral equation; Gronwall lemma; Ulam-Hyers stability.

### 1. INTRODUCTION

For the study of different Ulam types stability, there are various techniques in the literatures: exact solution approaches, fixed point approaches (weakly Picard operators,...), Gronwall's lemma approach, and so on. For the details on these approaches, we refer to [6, 8, 14, 15, 17, 18, 19] and the references therein. In this paper, based on the results presented in [14] and [17], we study the Ulam-Hyers stability of some ordinary differential equations by Gronwall lemma techniques.

### 2. PRELIMINARIES

**2.1. Basic notions in the Ulam-Hyers stability of differential equations.** Let  $(\mathbb{B}, |\cdot|)$  be a Banach space. Let  $\varepsilon > 0$ ,  $a \in \mathbb{R}$ , and  $b \in \mathbb{R} \cup \{+\infty\}$  with  $a < b$ . We denote by  $I$  an interval of the real axis ( $I := [a, b]$  or  $[a, b[$ , depending on the context).

Let  $f \in C(I \times \mathbb{B}, \mathbb{B})$  be a given continuous operator. We consider the following problems:

1) the differential equation

$$x'(t) = f(t, x(t)), t \in I, \quad (2.1)$$

with its solution set denoted by  $S_0$ ;

2) the differential inequation

$$|x'(t) - f(t, x(t))| \leq \varepsilon, t \in I, \quad (2.2)$$

with the solution set (for each  $\varepsilon > 0$ ) denoted by  $S_\varepsilon$ . Notice that a function  $y \in C^1(I, \mathbb{B})$  is a solution of (2.2) if and only if there exists a function  $g \in C(I, \mathbb{B})$  (which may depend on  $y$ ) such that

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- (i)  $|g(t)| \leq \varepsilon$ , for all  $t \in I$ ;
- (ii)  $y'(t) = f(t, y(t)) + g(t)$ , for every  $t \in I$ .

A solution to inequation (2.2) is called an  $\varepsilon$ -solution of equation (2.1).

The following concepts are important for our study in this paper (see [10, 18]).

**Definition 2.1.** The differential equation (2.1) is said to be Ulam-Hyers stable if there exists a real number  $C_f > 0$  such that, for each  $\varepsilon > 0$ , there exists a retraction  $r_\varepsilon : S_\varepsilon \rightarrow S_0$  satisfying

$$|y(t) - r_\varepsilon(y)(t)| \leq C_f \varepsilon, \text{ for each solution } y \in C^1(I, \mathbb{B}) \text{ of (2.2) and every } t \in I. \quad (2.3)$$

**Definition 2.2.** Differential equation (2.1) is said to be generalized Ulam-Hyers stable if there exists a function  $\theta_f \in C(\mathbb{R}_+, \mathbb{R}_+)$  with  $\theta(0) = 0$  such that, for each  $\varepsilon > 0$ , there exists a retraction  $r_\varepsilon : S_\varepsilon \rightarrow S_0$  satisfying

$$|y(t) - r_\varepsilon(y)(t)| \leq \theta_f(\varepsilon), \text{ for each solution } y \in C^1(I, \mathbb{B}) \text{ of (2.2) and every } t \in I. \quad (2.4)$$

**2.2. Gronwall lemmas.** In this paper, we need the following Gronwall lemmas (see [2, 3, 4, 5, 7, 12, 13, 14]).

**Lemma 2.1.** (Gronwall Lemma I.) Let  $J$  be an interval of the real axis,  $t_0 \in J$  and the functions  $h, k, u \in C(J, \mathbb{R}_+)$ . If

$$u(t) \leq h(t) + \left| \int_{t_0}^t k(s)u(s)ds \right|, \text{ for all } t \in J,$$

then

$$u(t) \leq h(t) + \left| \int_{t_0}^t h(s)k(s)e^{\left| \int_s^t k(\sigma)d\sigma \right|} ds \right|, \text{ for all } t \in J.$$

If, in addition,  $h$  is increasing, then ( $J := [a, b]$ )

$$u(t) \leq h(t)e^{\int_a^t k(s)ds}, \quad t \in [a, b].$$

**Lemma 2.2.** (Gronwall Lemma II.) Let  $h \in C([a, b], \mathbb{R}_+)$  and  $\beta > 0$  with  $\beta(b-a) < 1$ . If  $u \in C([a, b], \mathbb{R}_+)$  satisfies the relation

$$u(t) \leq h(t) + \beta \int_a^b u(s)ds, \text{ for } t \in [a, b],$$

then

$$u(t) \leq h(t) + \frac{\beta}{1 - \beta(b-a)} \int_a^b h(s)ds, \text{ for every } t \in [a, b].$$

### 3. AN HEURISTIC POINT OF VIEW ON THE ULAM-HYERS STABILITY OF A DIFFERENTIAL EQUATION

Let  $f \in C([a, b] \times \mathbb{B}, \mathbb{B})$ ,  $g \in C([a, b], \mathbb{B})$  and  $\varepsilon \in \mathbb{R}_+^*$ .

We consider the differential equations

$$x'(t) = f(t, x(t)), \quad t \in [a, b], \quad (3.1)$$

$$x'(t) = f(t, x(t)) + g(t), \quad t \in [a, b], \quad (3.2)$$

and the differential inequation

$$|x'(t) - f(t, x(t))| \leq \varepsilon, \quad t \in [a, b]. \quad (3.3)$$

For a function  $x \in C^1([a, b], \mathbb{B})$  and for given  $x_0 \in \mathbb{B}$ , we consider the Cauchy condition

$$x(a) = x_0. \quad (3.4)$$

We suppose that (see [2, 4, 7, 9, 12]):

(C) For each  $x_0 \in \mathbb{B}$ , Cauchy problem (3.1)+(3.4) has a unique solution, denoted by  $x(\cdot, x_0) \in C^1([a, b], \mathbb{B})$ ;

(PC) For each  $g \in C([a, b], \mathbb{B})$  and each  $x_0 \in \mathbb{B}$ , Cauchy problem (3.2)+(3.4) has a unique solution, denoted by  $x(\cdot, x_0, g) \in C^1([a, b], \mathbb{B})$ .

Let us consider the following subsets of  $C^1([a, b], \mathbb{B})$ :

$$S_0 := \{x(\cdot, x_0) \mid x_0 \in \mathbb{B}\},$$

$$S_\varepsilon := \{x(\cdot, x_0, g) \mid g \in C([a, b], \mathbb{B}), |g(t)| \leq \varepsilon, \forall t \in [a, b], x_0 \in \mathbb{B}\}.$$

It is clear that, in the conditions (C) and (PC),

- 1)  $S_0$  is the solution set of differential equation (3.1);
- 2)  $S_\varepsilon$  is the solution set of differential inequality (3.3).

Let  $y \in C^1([a, b], \mathbb{B})$  be a solution of (3.3). Then, there exists  $g \in C^1([a, b], \mathbb{B})$  with  $|g(t)| \leq \varepsilon$ ,  $\forall t \in [a, b]$ , such that  $y$  is a solution of differential equation (3.2). Let  $x(\cdot, y(a))$  be the unique solution to (3.1) with  $x(a) = y(a)$ .

For  $y$  and  $x(\cdot, y(a))$ , we have

$$y(t) = y(a) + \int_a^t f(s, y(s)) ds + \int_a^t g(s) ds, \quad t \in [a, b],$$

and

$$x(t; y(a)) = y(a) + \int_a^t f(s, x(s; y(a))) ds, \quad t \in [a, b].$$

The above relations imply that

$$|y(t) - x(t; y(a))| \leq \int_a^t |f(s, y(s)) - f(s, x(s; y(a)))| ds + (b-a)\varepsilon, \quad t \in [a, b]. \quad (3.5)$$

In some conditions on  $f$ , we can obtain estimations for  $|y(t) - x(t; y(a))|$ . For example, let us suppose that

(Lip) There exists  $L > 0$  such that

$$|f(t, u) - f(t, v)| \leq L|u - v|, \quad \forall t \in [a, b], \forall u, v \in \mathbb{B}.$$

With this condition, we have that

$$|y(t) - x(t; y(a))| \leq L \int_a^t |y(s) - x(s; y(a))| ds + (b-a)\varepsilon, \quad t \in [a, b].$$

From Gronwall Lemma I (see Lemma 2.1), the estimate follows

$$|y(t) - x(t; y(a))| \leq (b-a)e^{L(b-a)}\varepsilon, \quad t \in [a, b].$$

From the above considerations, for each  $\varepsilon > 0$ , we have a retraction,  $r_\varepsilon : S_\varepsilon \rightarrow S_0$ , defined by  $y \mapsto x(\cdot, y(a))$ , for which

$$|y(t) - r_\varepsilon(y)(t)| \leq c\varepsilon, \quad t \in [a, b],$$

where  $c = (b-a)e^{L(b-a)}$ .

Since condition (Lip) implies the conditions (C) and (PC), we have the following result.

**Theorem 3.1.** *Let us consider the differential equation (3.1). Suppose that the condition (Lip) holds. Then, for each  $\varepsilon > 0$ , there exists a retraction  $r_\varepsilon : S_\varepsilon \rightarrow S_0$  such that*

$$|y(t) - r_\varepsilon(y)(t)| \leq (b-a)e^{L(b-a)}\varepsilon, \quad \forall y \in S_\varepsilon \text{ and } \forall t \in [a, b],$$

*i.e., equation (3.1) is Ulam-Hyers stable.*

**Remark 3.1.** Let us take  $\mathbb{B} := \mathbb{R}^m$  and denote a norm on  $\mathbb{R}^m$  by  $|\cdot|$ . In this case, since all norms on  $\mathbb{R}^m$  are equivalent, if equation (3.1) is Ulam-Hyers stable with respect to a norm on  $\mathbb{R}^m$ , then it is Ulam-Hyers stable with respect to each other norm on  $\mathbb{R}^m$  (see [11, 16, 18]). If we denote by  $L_{|\cdot|}$ , the Lipschitz constant of  $f$  with respect to  $|\cdot|$ , then we have, in terms of the norm  $|\cdot|$ , the following estimation

$$|y(t) - r_\varepsilon(y)(t)| \leq (b-a)e^{L_{|\cdot|}(b-a)}\varepsilon, \text{ for all } y \in S_\varepsilon \text{ and } t \in [a, b].$$

For example, in the case that  $f(t, y(t)) = A(t)x(t)$ , where  $A \in C([a, b], \mathbb{R}^{m \times m})$  is a matrix function and  $|A(t)|$  is the corresponding matrix norm of  $A(t)$  with respect to the vector norm  $|\cdot|$ , we have

$$L_{|\cdot|} = \max_{t \in [a, b]} |A(t)|.$$

From Theorem 3.1, we have the following.

**Theorem 3.2.** *If  $A \in C([a, b], \mathbb{R}^{m \times m})$ , then the linear system of differential equations*

$$x'(t) = A(t)x(t), \quad t \in [a, b],$$

*is Ulam-Hyers stable.*

We have a similar result in the case  $\mathbb{B} := \mathbb{C}^m$ .

**Remark 3.2.** Let  $(\mathbb{B}, |\cdot|) := (l_2(\mathbb{R}), |\cdot|_2)$ . In this case, equation (3.1) is a countable system of differential equations (see [20]). In the corresponding (Lip) condition, this system is Ulam-Hyers stable.

**Remark 3.3.** Instead of condition (Lip), some authors (see, for example, [6]) considered the condition

$$(Lip(t)) \quad |f(t, u(t)) - f(t, v(t))| \leq L|u(t) - v(t)|, \text{ for every } u, v \in C([a, b], \mathbb{B}), \quad t \in [a, b].$$

It is clear that conditions (Lip) and (Lip(t)) are equivalent.

#### 4. SECOND ORDER DIFFERENTIAL EQUATIONS

For a better understanding of the Ulam-Hyers stability of  $n$ -order differential equations, we consider, for simplicity, the following second order differential equation

$$-x''(t) = f(t, x(t)), \quad t \in [a, b], \tag{4.1}$$

where  $f \in C([a, b] \times \mathbb{R})$ .

For  $g \in C[a, b]$ , we consider the differential equation

$$-x''(t) = f(t, x(t)) + g(t), \quad t \in [a, b], \tag{4.2}$$

and for  $\varepsilon > 0$ , the following differential inequation

$$|-x''(t) - f(t, x(t))| \leq \varepsilon, \quad t \in [a, b]. \tag{4.3}$$

Let us suppose that:

(C) for all  $x_0, x'_0 \in \mathbb{R}$ , there exists a unique solution, denoted by  $x(\cdot; x_0, x'_0) \in C^2[a, b]$  of (4.1), such that

$$x(a) = x_0, \quad x'(a) = x'_0,$$

(PC) for all  $g \in C[a, b]$ ,  $x_0, x'_0 \in \mathbb{R}$ , there exists a unique solution, denoted by  $x(\cdot; x_0, x'_0, g) \in C^2[a, b]$  of (4.2), such that

$$x(a) = x_0, \quad x'(a) = x'_0.$$

In conditions (C) and (PC),

$$S_0 := \{x(\cdot; x_0, x'_0) \mid x_0, x'_0 \in \mathbb{R}\}$$

is the solution set of (4.1) and

$$S_\varepsilon := \{x(\cdot; x_0, x'_0, g) \mid x_0, x'_0 \in \mathbb{R}, g \in C[a, b], |g(t)| \leq \varepsilon, \forall t \in [a, b]\}$$

is the solution set of (4.3).

Now, let  $y \in C^1[a, b]$  be a solution of (4.3). Then, there exists  $g \in C[a, b]$ ,  $|g(t)| \leq \varepsilon$ ,  $t \in [a, b]$ , such that  $y$  is a solution of (4.2). Let  $x(\cdot; y(a), y'(a))$  be the unique solution to (4.1). For  $y$  and  $x(\cdot; y(a), y'(a))$ , we have

$$y(t) = y(a) + y'(a)(t-a) + \int_a^t (s-t)f(s, y(s))ds + \int_a^t (s-t)g(s)ds$$

and

$$x(t; y(a), y'(a)) = y(a) + y'(a)(t-a) + \int_a^t (s-t)f(s, x(s; y(a), y'(a)))ds.$$

These imply that

$$|y(t) - x(t; y(a), y'(a))| \leq \int_a^t |f(s, y(s)) - f(s, x(s; y(a), y'(a)))| + \frac{1}{2}(b-a)^2 \varepsilon.$$

If we suppose, for example, the condition (Lip) for  $f$ , then

$$|y(t) - x(t; y(a), y'(a))| \leq \frac{1}{2}(b-a)^2 e^{L(b-a)} \varepsilon,$$

for all  $y \in S_\varepsilon$  and  $t \in [a, b]$ .

In the above conditions, we get the retractions

$$r_\varepsilon : S_\varepsilon \rightarrow S_0, \quad y \mapsto x(\cdot; y(a), y'(a)),$$

with

$$|y(t) - r_\varepsilon(y)(t)| \leq \frac{1}{2}(b-a)^2 e^{L(b-a)} \varepsilon,$$

for all  $y \in S_\varepsilon$  and  $t \in [a, b]$ .

Thus, by the above observations, we have the following result.

**Theorem 4.1.** *If condition (Lip) takes place, then differential equation (4.1) is Ulam-Hyers stable.*

Now, let us work in more restrictive conditions:

(B) for all  $\alpha, \beta \in \mathbb{R}$ , equation (4.1) has a unique solution, denoted by  $x(\cdot; \alpha, \beta) \in C^2[a, b]$ , such that

$$x(a) = \alpha, \quad x(b) = \beta.$$

(PB) for all  $g \in C[a, b]$  and all  $\alpha, \beta \in \mathbb{R}$ , the equation (4.2) has a unique solution, denoted by  $x(\cdot; \alpha, \beta, g) \in C^2[a, b]$ , such that

$$x(a) = \alpha, \quad x(b) = \beta.$$

In these conditions, we denote by

$$S_0 = \{x(\cdot, \alpha, \beta) \mid \alpha, \beta \in \mathbb{R}\}$$

the solution set of (4.1) and by

$$S_\varepsilon = \{x(\cdot, \alpha, \beta, g) \mid \alpha, \beta \in \mathbb{R}, g \in C[a, b], |g(t)| \leq \varepsilon, t \in [a, b]\}$$

the solution set of (4.3).

We remark that the operator  $\rho_\varepsilon : S_\varepsilon \rightarrow S_0$ , defined by  $y \mapsto x(\cdot; y(a), y(b))$  is a retraction of  $S_\varepsilon$  on  $S_0$ . Let us estimate  $|y(t) - \rho_\varepsilon(y)(t)|$ .

We have, in the terms of the Green function  $G(s, t)$  of the operator  $-x''$ , the following relations for  $y$  and  $x(\cdot; y(a), y(b))$ ,

$$y(t) = \frac{b-t}{b-a}y(a) + \frac{t-a}{b-a}y(b) + \int_a^b G(t, s)f(s, y(s))ds + \int_a^b G(t, s)g(s)ds,$$

$$t \in [a, b]$$

and

$$x(t; y(a), y(b)) = \frac{b-t}{b-a}y(a) + \frac{t-a}{b-a}y(b) + \int_a^b G(t, s)f(s, x(s; y(a), y(b)))ds,$$

$$t \in [a, b].$$

Recall that the Green function of the operator  $-x''$  is given by

$$G(t, s) = \begin{cases} \frac{(s-a)(b-t)}{b-a} & \text{if } s \leq t, \\ \frac{(t-a)(b-s)}{b-a} & \text{if } s \geq t. \end{cases}$$

The above relations imply that

$$|y(t) - x(t; y(a), y(b))| \leq \int_a^b G(t, s)|f(s, y(s)) - f(s, x(s; y(a), y(b)))|ds + \int_a^b G(t, s)|g(s)|ds \leq$$

$$\int_a^b G(t, s)|f(s, y(s)) - f(s, x(s; y(a), y(b)))| + \frac{(b-a)^2}{8}\varepsilon.$$

If we suppose, for example, the condition (Lip) for  $f$ , then

$$|y(t) - x(t; y(a), y(b))| \leq L \int_a^b G(t, s)|y(s) - x(s; y(a), y(b))|ds + \frac{(b-a)^2}{8}\varepsilon.$$

for all  $y \in S_\varepsilon$  and  $t \in [a, b]$ . Thus, by Gronwall Lemma II, (see Lemma 2.2), we get

$$|y(t) - x(t; y(a), y(b))| \leq \frac{(b-a)^2}{8}\varepsilon + \frac{(b-a)^3}{8}\varepsilon \frac{L \frac{b-a}{4}}{1 - L \frac{(b-a)^2}{4}} = \frac{(b-a)^2}{8} \left( 1 + \frac{L(b-a)^2}{4 - L(b-a)^2} \right) \varepsilon.$$

In view of the above, we get the following result immediately.

**Theorem 4.2.** *If condition (Lip) takes place and  $\frac{L(b-a)^2}{4} < 1$ , then differential equation (4.1) is Ulam-Hyers stable.*

**Remark 4.1.** For related results, we refer to [15, pp. 131-132].

Let us also notice that, in general,  $r_\varepsilon \neq \rho_\varepsilon$ , as we will see in the following example.

**Example 4.1.** Let us consider the differential equations

$$-x'' = -x, \quad t \in [0, 1]$$

and

$$-x'' = -x + 1, \quad t \in [0, 1].$$

Here  $g(t) = 1$ . Then, for  $\varepsilon \geq 1$ , the function  $y(t) = e^t + 1$  is a solution of the differential inequation

$$|-x'' + x| \leq \varepsilon.$$

If we consider the initial conditions

$$\begin{cases} y(0) = 2, \\ y'(0) = 1, \end{cases}$$

then, by an easy calculation, we get

$$x(t; 2, 1) = \frac{3}{2}e^t + \frac{1}{2}e^{-t} := r_\varepsilon(y)(t).$$

On the other hand, if we consider the bilocal conditions

$$\begin{cases} y(0) = 2, \\ y(1) = e + 1, \end{cases}$$

then

$$x(t; 2, e + 1) = \frac{2e^{-1} - e - 1}{e^{-1} - e}e^t + \frac{1 - e}{e^{-1} - e}e^{-t} := \rho_\varepsilon(y)(t).$$

## 5. DIFFERENTIAL EQUATIONS WITH SOLUTIONS IN $C^1([a, +\infty[, \mathbb{B})$

Let  $f \in C([a, \infty[, \times \mathbb{B}, \mathbb{B})$ ,  $g \in C([a, +\infty[, \mathbb{B})$ ,  $\varepsilon > 0$  and  $\varphi \in C([a, +\infty[, \mathbb{R}_+^*)$ . We consider the differential equations

$$x'(t) = f(t, x(t)), \quad t \in [a, +\infty[, \quad (5.1)$$

$$x'(t) = f(t, x(t)) + g(t), \quad t \in [a, +\infty[, \quad (5.2)$$

and the differential inequations

$$|x'(t) - f(t, x(t))| \leq \varepsilon, \quad \forall t \in [a, +\infty[, \quad (5.3)$$

$$|x'(t) - f(t, x(t))| \leq \varepsilon \varphi(t), \quad \forall t \in [a, +\infty[, \quad (5.4)$$

and

$$|x'(t) - f(t, x(t))| \leq \varphi(t), \quad \forall t \in [a, +\infty[. \quad (5.5)$$

As in Section 3, we suppose (see also [1, 21]) that

(C) for each  $x_0 \in \mathbb{B}$  the equation (5.1) has a unique solution, denoted by  $x(\cdot, x_0) \in C^1([a, \infty[, \mathbb{B})$ , such that  $x(a) = x_0$ .

(PC) the equation (5.2) satisfies condition (C) for each  $g \in C([a, +\infty[, \mathbb{B})$ .

Let  $S_0$  be the solution set of (5.1),  $S_\varepsilon$ ,  $S_{\varepsilon, \varphi}$ ,  $S_\varphi$  the solution set of (5.3), (5.4) and (5.5), respectively. As in Section 3, we consider the retractions

$$r_\varepsilon : S_\varepsilon \rightarrow S_0, \quad r_{\varepsilon, \varphi} : S_{\varepsilon, \varphi} \rightarrow S_0, \quad r_\varphi : S_\varphi \rightarrow S_0.$$

For  $r_\varepsilon$ , we have the estimate

$$|y(t) - r_\varepsilon(y)(t)| \leq (t - a)e^{L(t-a)}\varepsilon, \quad \forall t \in [a, +\infty[.$$

The problem is that this estimate is not of Ulam-Hyers type.

Moreover, by simple examples, we observe that, in general, the differential equations is not Ulam-Hyers stable ([8, 15]) on  $[a, +\infty[$ .

**Example 5.1.** We consider the case  $\mathbb{B} := \mathbb{R}$  and  $f = 0$ .

In this case, we have

$$x'(t) = 0, \quad t \in [a, +\infty[ \quad (5.6)$$

and

$$|x'(t)| \leq \varepsilon, \quad t \in [a, \infty[. \quad (5.7)$$

The function  $y(t) = t\varepsilon$ ,  $t \in [a, +\infty[$  is a solution of (5.7) and all solutions of (5.6) are  $x = c$ ,  $c \in \mathbb{R}$ . We remark that  $|y(t) - c| \rightarrow \infty$  as  $t \rightarrow \infty$ .

The function  $y(t) = \varepsilon \int_a^t \varphi(s)ds$  is a solution of

$$|x'(t)| \leq \varepsilon \varphi(t), \quad \text{for } t \in [a, +\infty[. \quad (5.8)$$

In this case,

$$|y(t) - 0| = \left| \varepsilon \int_a^t \varphi(s)ds \right| = \varepsilon \int_a^t \varphi(s)ds.$$

To have an estimate of Ulam-Hyers-Rassias type, the function  $\varphi$  must satisfy a strong restrictive condition (see [8, 15]) of the following form:

(CC) there exists  $\lambda > 0$  such that  $\int_a^t \varphi(s)ds \leq \lambda \varphi(t)$ ,  $\forall t \in [a, +\infty[$ .

So, nothing remains but to estimate

$$|y(t) - \rho_{\varepsilon, \varphi}(y)(t)|$$

and

$$|y(t) - \rho_\varphi(y)(t)|.$$

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